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Training Requirements for the Battlefield Management System (BMS):

A Preliminary Analysis

ARI Field Unit at Fort Knox, Kentucky
Training Research Laboratory

May 1987



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# U. S. ARMY RESEARCH INSTITUTE FOR THE BEHAVIORAL AND SOCIAL SCIENCES

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EDGAR M. JOHNSON Technical Director WM. DARRYL HENDERSON COL, IN Commanding

Technical review by

Michael W. Adamson, Directorate of Combat Developments, Fort Knox Christine R. Hartel
Donald R. Lampton
James W. Lussier



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# Training Requirements for the Battlefield Management System (BMS): A Preliminary Analysis

Carl W. Lickteig

ARI Field Unit at Fort Knox, Kentucky
Donald F. Haggard, Chief

Training Research Laboratory

Jack H. Hiller, Director

U.S. ARMY RESEARCH INSTITUTE FOR THE BEHAVIORAL AND SOCIAL SCIENCES
5001 Eisenhower Avenue, Alexandria, Virginia 22333-5600

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Exploratory Development, Human Performance
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To ensure that the U.S. Army's future weapon systems are usable by our soldiers, the Army Research Institute for the Behavioral and Social Sciences (ARI) performs behavioral research to provide guidelines and specifications for matching equipment designs with soldier capabilities and limitations. the ARI Field Unit at Fort Knox, the Future Battlefield Conditions Team conducts applied research to enhance soldier preparedness through identification of future weapon systems and the methods for training to meet those systems.

This product by the ARI Field Unit at Fort Knox was prepared under Science and Technology Task 3.5.1, "Training Requirements for NBC and the Future Integrated Battlefield," at the request of the TRADOC System Manager (TSM) for the MIAI Block II. ARI's involvement in research on future battlefield conditions supports the Memorandum of Understanding (MOU) between ARI and the U.S. Army Armor Center and School (USAARMC&S) on Land Battle Test Bed research signed 9 January 1986. The results of this effort were briefed to COL Burgess (TSM-TANK) on 6 March 1987, and the report was provided to the TSM office in response to questions addressed in Tab D of the System MANPRINT Management Plan (SMMP).

> Elgn H Henen EDGAR M. JOHNSON

Technical Director

# TRAINING REQUIREMENTS FOR THE BATTLEFIELD MANAGEMENT SYSTEM (BMS): A PRELIMINARY ANALYSIS

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# TRAINING REQUIREMENTS FOR THE BATTLEFIELD MANAGEMENT SYSTEM (BMS): A PRELIMINARY ANALYSIS

#### INTRODUCTION

#### Background

For the current stage of product improvements to the MIAI tank, the Army has authorized the production of a set of enhancements collectively labelled Block II. Anticipated upgrades to any weapon system, however, may result in unanticipated complications, even system degradation, unless their design and development efforts systematically address product-related manpower and personnel integration (MANPRINT) issues. The goal of the MANPRINT program, therefore, is to improve total system (soldier and equipment) performance by the continuous integration of human factors engineering, manpower, personnel, training, system safety and health hazard considerations throughout the materiel development and acquisition process. One important MANPRINT issue is the timely identification of training requirements -- what needs to be trained, when and where--associated with the system or subsystem under development. This report identifies training requirements associated with one of the Block II components, a first-generation Battlefield Management System (BMS) which is expected to partially automate the command, control and communication  $(c^3)$ of lower echelons.

In support of MANPRINT, The Army Research Institute for the Behavioral and Social Sciences (ARI) has initiated a wide-ranging program to identify, test and revise MANPRINT support technologies. ARI's responsibility for providing research and development (R&D) on MANPRINT-related analytical technologies is part of ARI's mission as an element of the Office of the Deputy Chief of Staff for Personnel (ODCSPER). ARI's approach to meeting MANPRINT requirements has focused on defining the functional characteristics of a system and viewing system operators as extensions of the system. This analysis of BMS training requirements is consistent with this approach and has focused on the functional characteristics of the anticipated BMS system as related to the task requirements of a typical BMS operator.

Preliminary BMS training requirements, the subject of this report, were identified by ARI-Knox at the request of the MANPRINT Joint Working Group (JWG) for the MIAI Block II. The analysis was conducted to answer, at least partially, some of the training and personnel questions raised by the JWG in their preparation of the System MANPRINT Management Plan (SMMP) for MIAI Block II.

In general, Block II enhancements to the MIAI include: enhanced survivability, data bus, navigation system (POSNAV), CO<sub>2</sub> laser range finder (LRF), driver's and commander's independent thermal viewers (DTV, CITV), improved commander's weapon station, and intervehicular information system (IVIS), IVIS, a starter set for BMS, is expected to initiate the automation of C<sup>3</sup> functions for lower echelon, battalion-down, Armor units.

As noted in the Operational and Organization (0&0) Plan for BMS, the pace of the Air Land Battle and the numerical superiority of opposing forces

(OPFOR) require significant improvements in the U.S. Army's command, control and communication ( $C^3$ ) capabilities. Although the MIAI tank is generally regarded as the most lethal and mobile armored weapon system in the world, its capability is severely constrained by repetitive, time consuming and manual  $C^3$  functions. A primary goal of the immediate Block II additions to the MIAI, therefore, is to significantly upgrade this weapon system's performance by technological enhancements in the areas of  $C^3$ .

The training requirements for IVIS are the immediate concern of this analysis, and not the other Block II enhancements. Training requirements for each of the Block II enhancements are anticipated and shall be integrated with the current findings by the JWG in their preparation of the SMMP.

This subjective analysis of BMS training requirements anticipated three successive generations of lower echelon automated C<sup>3</sup> systems that are anticipated as a result of technological advances enabling BMS product improvements. In the near term, IVIS has been designated as the precursor to BMS. In midterm, BMS is expected to emerge with the addition of a digitized terrain data base to IVIS. In the far term, the addition of artificial intelligence (AI), with tactical decision making capabilities, to BMS is expected to culminate in an objective C<sup>3</sup> system referred to in this report as BMS/AI.

Training requirements were identified by analyzing changes in the platoon leader's (PLT LDR) task requirements associated with each of these three generations of automated C<sup>3</sup> systems. The primary objectives of this analysis were to identify: the wide range of PLT LDR's tasks that may be affected by these automated C<sup>3</sup> systems; the extent to which the difficulty of training and performing these tasks might be increased, reduced or eliminated by automation; and, the nature and configuration of training devices that might be needed to meet these training requirements.

#### **Emerging Systems**

Lower echelon automated C<sup>3</sup> systems such as IVIS and BMS are emerging systems. Currently, IVIS is undergoing Engineering Design Tests by the contractor (EDT-C). Design specifications for IVIS have not been formulated, and the EDT-C version of IVIS is the first time that a prototype has been developed to directly test IVIS-based C<sup>3</sup> functions. With respect to BMS development, the O&O plan for BMS has yet to be approved by TRADOC. BMS design specifications have not been established, but several prototype BMS systems have been developed to assess user requirements. Most notably, Texas Instruments provided a prototype BMS that was used to identify user information requirements (Jobe, 1986) and Lockheed developed another BMS prototype that was used to identify user interface requirements (Lickteig, 1986). ARI's involvement with these prototypes, and the early formulation of automated C<sup>3</sup> functional requirements at the lower echelon (Blasche and Lickteig, 1984), served as the basis for this preliminary analysis of BMS training requirements.

Both the design and development of lower echelon automated  ${\tt C}^3$  is iterative. The proposed BMS, as specified in the 0&O Plan, is an ambitious concept that has already slipped well beyond the original developmental milestones that projected BMS fielding in 1988. Monetary and technological

constraints have forced BMS combat developers to both lower their near term requirements, and extend their projected acquisition schedule. IVIS, for example, was initiated in response to these constraints as a BMS starter set, yet even IVIS is not scheduled for MIAI production cut-in until mid 1990. In view of these contraints, and the complexities inherent in the materiel acquisition process, it was decided that the most useful analysis of BMS training requirements would be one tailored to the successive generations, or levels, of C<sup>3</sup> automation anticipated.

#### Levels of Automation

For this preliminary analysis, training requirements unique to three cumulatively automated C<sup>3</sup> systems—IVIS, BMS, BMS/AI—were identified. Before describing each of these levels in some detail, it should be noted that the latter distinction between BMS and BMS/AI is not shared by all members of the combat developments community. A more commonly held assumption is that the tools of artificial intelligence will be sufficiently refined to meet the currently projected schedule of BMS development. But both commercial and military ventures into AI have generated new respect for the information processing capabilities of human intelligence, and in particular the complexity of perceptual and decision making processes. In the application of AI to tactical information processing, this complexity is compounded by the turbulent and unpredictable conditions of the battlefield and the criticality of military decisions and operations. The current analysis, therefore, postulates AI decision making capabilities as a far term improvement, and BMS/AI as a distinct level of automated C<sup>3</sup> systems.

The distinction made in this report between BMS and BMS/AI is arbitrary, and not intended to represent official policy of the Department of the Army. The purpose of the distinction is simply to ensure a more comprehensive front-end analysis (FEA) of the differential training requirements that may arise in the iterative development and acquisition of lower echelon automated C<sup>3</sup> systems. More detailed descriptions of each of these three levels will now be presented.

IVIS, an Armor dedicated weapon subsystem, is an integrated complex of technologies for acquiring, processing, storing and transmitting lower echelon battlefield information. The automated C<sup>3</sup> capabilities of IVIS will be supported by a 1553 data bus that allows continuous monitoring and updating of information from the FM radio nets, the turret and hull network boxes, and selected Block II components such as POSNAV, CO2 LRF and CITV. This information should be made available to the user by way of a monochromatic display panel, and presented in both graphic and alphanumeric formats. The display panel will be partitioned into a number of smaller display areas with each area dedicated to distinct display features and control functions. The actual data and control fields available on IVIS have not yet been specified, nor has the overall configuration and format of the operator's display With the exception of the digital terrain data, the protopanel interface. type BMS display presented in Figure 1 depicts the general display configuration and control functions anticipated for both IVIS and BMS.

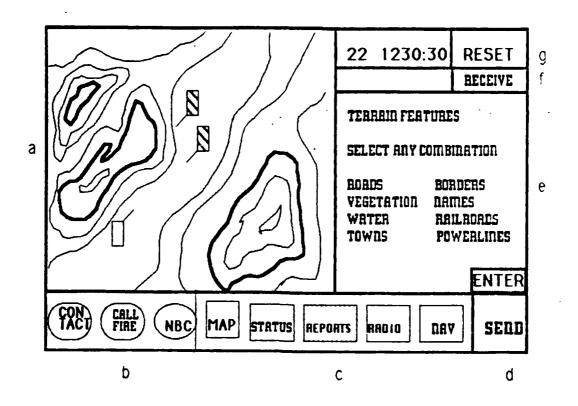


Figure 1. Prototype BMS display (a = map display; b = automatic function keys; c = main menu keys; d = transmit key; e = variable menu display; f = message display; g = date and time display).

Current projections assume that digital terrain data will not be available for IVIS. The most likely alternative is that the "map" area designated for IVIS will display a military grid matrix. Within this grid matrix the user will be able to generate, receive, store, and transmit graphic data such as operational overlays, control measures, and unit symbology. The grid referencing system will provide correspondence between these overlays and the standard paper copy maps. An alternative, and more effective IVIS system would store and provide digitized maps (not digital terrain data) and update map presentations by means of the grid referencing system. In either event, the assumption made for this analysis is that IVIS will not provide the "flexible" map expected for BMS, or the "smart" map anticipated for BMS/AI.

The submenu region of the proposed IVIS display will be primarily designed for textual formats. Alphanumeric data in the form of messages, reports, orders and alerts will be composed, transmitted and received in this region of the user's interface display. The input device, and use of preformatted versus free field entries, are important training requirement factors that have not been resolved. The assumptions made for this analysis are that a touch-sensitive interface or mouse and trackball input device will be used, and that textual entries will be preformatted and menu-driven.

All IVIS-based communications, graphic and alphanumeric, will be transmitted and received by way of digital burst signals transmitted by frequency hopping single channel ground/airborne radio systems (SINCGARS). IVIS storage and interface features will allow users to compose an entire order or report before transmission, verify its accuracy, and then digitally transmit the entire message in millisecond bursts. Both net access and interference will be monitored automatically by IVIS, and call signs and authentication procedures should be automatically annotated and processed for intervehicular communications.

BMS. A primary enhancement assumed for BMS, over IVIS, in the near term is the addition of digitized terrain data at 1:50,000 scale. Currently, Defense Mapping Agency (DMA) data at Level 1 (1:50,000) are not available except for very limited regions of the earth's terrain. In addition, the MIL-STD-1553 data bus supporting IVIS is not powerful enough to process this volume of data. But when automated C<sup>3</sup> systems are enhanced with digital terrain data, significant advances in automating C<sup>3</sup> are projected. These advances are anticipated primarily because terrain visualization is one of the most difficult of all military tasks to perform (Barsam & Simutis, 1985; Rogers & Cross, 1981) and because battlefield geometry is fundamentally spatial, not textual, data. Consider the difficulty of giving someone directions with or without the aid of a map or other graphic aids.

The geometry of the battlefield is a critical component of nearly all C<sup>3</sup> communications, and a digital terrain data base will significantly automate and synchronize lower echelon map and operational overlay information. Terrain visualization will be, at least partially, automated by graded elevation shadings and horizontal or perspective views of the terrain. Map interpretation will be further automated by selective call-up and delete capabilities which are critical for avoiding clutter on the relatively compressed size of the display interface. Selective call-up and delete features are also instrumental in allowing BMS users to tailor their map displays with respect to both individual and situational factors.

Finally, the digitized terrain data base will automate the process of both extracting and inserting tactical information. Line-of-Sight (LOS) and trafficability algorithms, for example, will significantly automate terrain analysis. Graphic presentations of both friendly and enemy weapon system characteristics such as range, elevation and azimuth will greatly assist the excecution of such tasks as the preparation of range cards, sector sketches and fire control plans. This analysis of training requirements will more explicitly define the extent of this automation over a cross-section of PLT LDR tasks.

In conclusion, it is noted that the aforementioned BMS manipulations of digital terrain data are achieved by algorithmic transformations of the data base, and such transformations are not regarded as manifestations of artificial intelligence.

BMS/AI. While currently high risk and even unforeseen technological advances may be included in later BMS product improvements, this analysis anticipates that the most significant enhancement in long-term automated  $C^3$  will be artificial intelligence. In the area of automated  $C^3$ , the capstone of an AI system should provide an optimal tactical decision (e.g., plan of

action) that is based on integrated knowledge bases, expert rule-based protocols and real-time battlefield intelligence data. For a more complete discussion of the data-base and processing requirements for AI in an applied Armor setting see Harris, Fuller, Dyck and Rogers (1985).

This tactical decision making capability of AI is significantly more comprehensive and complicated than the piece-meal decision aids anticipated for BMS without AI such as the LOS and trafficability functions previously discussed. Once a tactical decision has been formulated by BMS/AI, the system should be able to automatically tailor and transmit this information (e.g., operations order [OPORD], fragmentary order [FRAGO]) in detail appropriate to both lower and upper echelons. As the execution of this plan unfolds, such as the crossing of phase lines or contact with the enemy, the C<sup>3</sup> system should be automatically monitoring, updating and re-analyzing the tactical situation.

As the subsequent analysis of training requirements suggests, this level of  ${\tt C}^3$  automation may significantly reduce the task load and training requirements associated with the PLT LDR position. As stated previously, BMS/AI is a far term  ${\tt C}^3$  system that is included in the present analysis to ensure a more comprehensive FEA and to more explicitly identify potential AI applications for lower echelon  ${\tt C}^3$ .

#### **METHODOLOGY**

#### Task Requirements

Training requirements must be based on task requirements. This analysis of BMS training requirements is based on the task requirements associated with the PLT LDR's position. The PLT LDRs position was selected for several reasons. First, there has been considerable speculation that the actual "fighters" on the battlefield will have neither the time or inclination to utilize automated C<sup>3</sup> systems. It is assumed that as levels of C<sup>3</sup> automation increase, these front-line personnel will be relieved of their more burdensome C<sup>3</sup> duties and thereby more capable of pressing the conflict. Secondly, as front-line personnel, PLT LDRs collectively possess a firsthand knowledge of the combat situation that is critical to informed C<sup>3</sup>. And finally, because of front-line attrition and the relatively limited military background of a PLT LDR the training requirements associated with this position are of particular importance.

The task requirements associated with the PLT LDR position were taken from MTP 17-15-1, The Tank Platoon Mission Training Plan (1985). While this is both an individual and collective training plan, the tasks and standards associated with collective platoon performance are central to the PLT LDR's responsibilities for  $C^3$ . This MTP provides a relatively complete list of the tactical training requirements associated with the platoon leader's position. This MTP was selected as the source document for this analysis because of its emphasis on tactical training and its inclusion of training and evaluation outlines (T&EO) which list all tasks, subtasks, and supporting tasks required for mission accomplishment.

A representative cross-section of PLT LDR tasks, and all C<sup>3</sup> tasks, listed in 17-15-1 were selected for this analysis and are presented in Table 1. The tasks in Table 1 are combined under three fundamental categories of maneuver warfare: Command, Control and Communication; Force Movement; and Offensive and Defensive Operations. For purposes of exposition, some of the original categories listed in 17-15-1 have been consolidated under the Table 1 headings. For example, Perform a Nuclear Contaminated Area Crossing is presented under Force Movement rather than a separate NBC category, and Offensive and Defensive Operations are combined into one category.

Table 1
Platoon Leader's Tasks by Category

Command, Control & Communication	Force Movement	Offensive/Defensive Operations
	TOTAL MOVEMENT	<u> </u>
Perform Platoon Leader	Perform Tactical Road	Execute a Hasty
Reconnaissance	March	Attack
Provide C <sup>2</sup> of a Platoon	Execute Actions at a	Perform Assault
Perform Tactical Planning	Halt	Force Activities
Perform Contact Point	Execute Traveling	Assault an OPFOR
Activities	Perform a Nuclear Con-	Position
Conduct Rehearsals for	taminated Crossing	Perform Consolida-
Mission	· ·	tion Activities
		Occupy a Battle
		Position

#### Training Requirements

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Given the developmental nature of the lower echelon C<sup>3</sup> systems, this analysis was based on the primary functional capabilities anticipated for each of the three levels of automated systems under consideration -- IVIS, BMS, BMS/AI. Until design specifications are formulated and operable systems are developed, a quantitative and objective task and skill analysis (TSA) of the human performance required on each system can not be prepared. This preliminary analysis has been based on C<sup>3</sup> system functions and capabilities as previously discussed, user information and interface requirements obtained (Jobe, 1986; Lickteig, 1986) using BMS prototypes, and the automated capabilities projected in the BMS O&O Plan. This subjective analysis of training requirements was originally performed by ARI personnel and then reviewed by subject matter experts (SMEs) from the Directorate of Combat Developments (DCD).

The primary objectives of this analysis were to identify the range and nature of PLT LDR tasks affected by these automated C<sup>3</sup> systems and the extent to which the performance of these tasks might become easier, more difficult or at least partially eliminated by automation. The analysis also addressed the issue of training devices by identifying which of the PLT LDR tasks affected by automated C<sup>3</sup> could be trained by stand-alone training devices versus which tasks would require an interactively, networked configuration of

training devices. Other training requirements considered in this analysis, but not included in Appendix A, were training media, training site, and personnel assignment and selection.

#### Rating System

The results of this analysis for these primary objectives are presented in Appendix A. Before presenting these results, a brief explanation of the table headings and entries is provided below and summarized in Table 2. The general heading of Appendix A begins with the list of PLT LDR tasks in the first column. Subheadings within this column indicate, in succession, the functional category (e.g., C<sup>3</sup>, Force Movement), the primary task being analyzed, and finally the subtasks, standards and supporting tasks included under the primary task. The next three columns of the table heading specify, in order, the three levels of C<sup>3</sup> systems addressed by this analysis—IVIS, BMS, and BMS/AI. The final column in the table heading addresses the issue of training device configuration, stand-alone or networked training devices. This issue of device configuration was not considered specific to any of the three levels of C<sup>3</sup> systems under consideration; the recommendations concerning training device configurations apply to all three levels of automated C<sup>3</sup> systems.

This preliminary analysis of training requirements for each of the primary tasks listed in Table 1 also included all of the subtasks, standards and supporting tasks required for execution of the primary task. Training requirements for all subtasks, standards and supporting tasks are therefore also included in Appendix A. The wide range of tasks included in the inventory are expected to provide a representative sample of the tasks required of PLT LDRs and an index of the pervasive impact of automated C<sup>3</sup> at the lower echelon.

The first requirement, COMMONALITY, indicates whether the training requirement for the task in question is the "same" (S,s) as conventional training or "different" (D,d) do to the introduction of an automated C<sup>3</sup> system. Tasks were rated as "different" when either the procedures or the tools for executing a task were affected by an automated C<sup>3</sup> system. The task of map reconnaissance, for example, was rated as "same" under IVIS which does not provide a digital map display. Platoon leaders equipped with IVIS must still refer to their paper maps to perform map reconnaissance. Under BMS, however, this task was rated as "different" although the platoon leader must analyze the same terrain features currently considered for map reconnaissance. But with the digital map display of BMS the platoon leader can selectively tailor his map to more directly and systematically analyze the tactical aspects of key terrain (e.g., line-of-sight, trafficability etc.).

Upper case letters in Appendix A indicate primary tasks and lower case letters are used for all subtasks, standards and supporting tasks. Ratings for the primary task are provided as a summary indicator of the  ${\bf C}^3$  system's impact across all subordinate and supporting tasks. When performance of a task has been completely automated by an advanced  ${\bf C}^3$  system, this column has been left blank to indicate that performance of the task has been eliminated and, therefore, no significant training requirement may exist (except for degraded modes).

The second requirement, Difficulty, indicates whether the automated C<sup>3</sup> system has made the task "easier" (E,e) or "potentially harder" (H?,h?) to perform, or if the task has been "partially automated" (PA,pa) or completely "automated" (A,a). IVIS, for example should make a number of PLT LDR tasks easier by providing check lists and initiating cues to facilitate task performance without actually automating or eliminating any of the task components. On the other hand, preparing textual portions of a report or order using message formats and menus may be more difficult than conventional voice (FM radio) procedures. To indicate that these tasks may increase task difficulty they are rated as potentially harder (h?) than conventional reporting requirements. Finally, the graphic portions (e.g., operational overlays) of a PLT LDR's order or report on IVIS will be manually generated but automatically transmitted and, therefore, are listed as partially automated (pa). When the task has been analyzed as the "same" under Commonality no entry was included under Difficulty, to more clearly indicate where changes in PLT LDR training requirements were anticipated.

Table 2

Description of Training Requirement Ratings in Appendix A

Requirement	Rating	Entry	Issues
Commonality	Same	s	Is the PLT LDRs task using an
·	Different	đ	automated C <sup>3</sup> system, the same or different than conventional task performance?
Difficulty	Easier	e	Is the PLT LDRs task easier,
-	Potentially Harder	h?	harder, partially automated or
	Partially Automated	рa	completely automated using the
	Automated	а	automated C <sup>3</sup> system?
Configuration	Stand-Alone	*	Can the PLT LDRs task be
-	Network	*	trained using a stand-alone automated C <sup>3</sup> system, or must the C <sup>3</sup> system be networked for intervehicular transmissions?

The final training requirement included in Appendix A, Configuration, indicates whether the task in question can be trained with an independent or "stand-alone" (SA,sa) training device or simulator, or whether training for the task will require that a number of training devices be linked together to form a communication "network" (N,n). Tasks rated as "same" across all systems, indicating no change in task or training requirements, were not assigned a rating under this column.

Additional training requirements considered in this analysis such as training media, training site, and personnel selection and assignment problems are discussed in the following section.

#### RESULTS AND DISCUSSION

Results are based on the training requirement ratings provided in Appendix A. All ratings were reviewed by SMEs from the Directorate of Combat Developments. Percentages are based on the relative frequency of a given rating across all tasks, subtasks, and supporting tasks appearing in Appendix A. Results are limited to the tasks included in MTP 17-15-1 which focuses on the tactical training requirements for platoons and platoon leaders.

#### Task Commonality

Automated command and control systems will affect a wide range of PLT LDR tasks and the training requirements for these tasks. Of particular interest is the impact of automated C<sup>3</sup> systems on the training requirements for the category of PLT LDR tasks specifically designated as C<sup>3</sup>. This analysis found that even a first-generation C<sup>3</sup> system, IVIS, will change the PLT LDR's task and training requirements for over 50% of the C<sup>3</sup> tasks and subtasks listed in Appendix A. As the level of automation increases with BMS and BMS/AI, over 90% of these tasks and subtasks will be affected.

This change in training requirements is clearly not limited to those tasks formally included by 17-15-1 under the category of C<sup>3</sup>, but extends-albeit to a lesser extent--throughout the sample of tasks included under the categories of Force Movement, Offensive Operations and Defensive Operations. The majority of all tasks considered under each of the PLT LDR functional categories will be performed differently when the more advanced C<sup>3</sup> systems, BMS and BMS/AI, are fielded. The pervasive impact of these more advanced C<sup>3</sup> systems on PLT LDR training requirements may be best summarized by noting that only 10-15% of all tasks and subtasks listed in Appendix A were rated "same" or unaffected by the objective system, BMS/AI.

#### Task Difficulty

Automated command and control systems will significantly reduce the difficulty of performing and training PLT LDR tasks, and the more advanced systems will at least partially eliminate many of these tasks through automation. IVIS, for example, when considered across all categories of PLT LDR performance listed in Appendix A was found to make "easier" approximately 25% of the task and subtask entries, and "partially automate" an additional 25%. Tentative ratings of "harder" (h?) were projected only for a few IVIS-based tasks, namely, the preparation of textual reports and orders. On the other hand, only one IVIS-based task, Determine a Location, was rated as completely "automated"—a function of IVIS's interface with the POS NAV system.

As the levels of automation increase with later-generation  ${\tt C}^3$  systems, approximately 60% of the BMS-based PLT LDR tasks were rated as either

"partially automated" or completely "automated," and 80% of the BMS/AI PLT LDR tasks were rated as "partially automated" or completely "automated." More specifically, within the C<sup>3</sup> category, the cumulative impact of these later-generation C<sup>3</sup> systems should actually eliminate a sizeable portion of the PLT LDR task requirements. The objective system, BMS/AI, may result in the complete automation of the majority of all C<sup>3</sup> tasks and subtasks listed in Appendix A.

The effect of these automated functions on training requirements must address the issue of system operability. Assuming fully operable C<sup>3</sup> systems, the training requirements would be significantly reduced for the majority of all tasks, and eliminated for many additional tasks. Degraded C<sup>3</sup> systems, per se, should not significantly impair conventional PLT LDR task performance (i.e., retention of voice FM nets), to the extent that PLT LDR's have been trained for degraded conditions and have not become overly dependent on automated capabilities.

#### Device Configuration

Many of the tactical training requirements for the PLT LDR's utilization of automated  $C^3$  systems can be met using stand-alone  $C^3$  training devices. This issue of training device configuration is an important aspect of  $C^3$  training requirements with respect to the allocation of training resources. In particular, the analysis suggests that tactical planning and report preparation can be addressed by independent training devices. Within the category of  $C^3$  platoon leader tasks this analysis found that the majority of these tasks can be trained, at least at the earliest stages of training with stand-alone  $C^3$  devices.

Over all the Appendix A PLT LDR functional categories, however, only approximately 25% of the tasks can be supported by stand-alone training devices. At least 60% of these tasks will require that C<sup>3</sup> training systems be "networked" to simulate intervehicular transmissions. Training requirements for the remaining 10-15% of the Appendix A entries, as previously noted, were rated as "same" or unaffected by the fielding of automated C<sup>3</sup> systems.

#### Additional Training Requirements

Key training requirement issues are the selection of training media and the design and development of training devices. Given the computer-based nature of these automated C<sup>3</sup> systems, an ideal training media would appear to be computer-based instruction (CBI). Fortunately CBI is an integral component of the Automated Classroom concept which is currently being implemented by the US Army Armor Center (USAARMC). And many of the hardware resources for this training media may soon be available at both institutional and reserve component training sites. As the analysis has indicated, however, training for many of the PLT LDR's tasks will require an interactive network of C<sup>3</sup> training devices and this is a resource intensive configuration particularly with respect to supporting hardware. Software and courseware packages for simulating and training automated C<sup>3</sup> system functions must be anticipated, and are identified as important training requirement issues to be addressed by the SMMP.

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Embedded training, the integration of a training package into the actual weapon system, is also identified as a critical training requirement to be included in the SMMP. The instructional potential of computer-based systems should result in the design specification of embedded training for these automated  ${\bf C}^3$  systems to support both unit and sustainment training. The cost-effectiveness of both CBI and embedded training for reducing the need for instructor and institutional resources provides additional support to this requirement.

Another important training requirement issue is determining the location or site in which training activities might take place. The current analysis has focused on a distinction between classroom versus field training locations. This analysis suggests that the majority of PLT LDR tasks considered can be initially trained in a classroom or institutional setting. More specifically, all of the tasks listed under the C<sup>3</sup> category, with the exception of several tasks requiring ground reconnaissance or navigation, appear suitable for at least initial training in the classroom. For the Offensive and Defensive categories, PLT LDR tasks such as tactical planning, the issue of the plans, and the coordination of plans among echelons can all be initially trained in a classroom equipped with C<sup>3</sup> training devices. In general, tasks requiring field training sites are terrain and weapon system dependent such as the actual execution of movement, occupation and assault operations.

A final training requirement issue is the identification of potential training and assignment problems. As indicated in Appendix A the proposed automated C<sup>3</sup> systems may require that users submit and receive textual reports, orders and messages. To the extent that voice transmissions are eliminated, automated C<sup>3</sup> systems may require substantially more training time and resources than conventional C<sup>3</sup>. While voice synthesis and recognition capabilities may be sufficiently advanced for integration into BMS and BMS/AI, they are not anticipated for IVIS. Directly related to this issue of textual rather than vocal communication protocols, potential assignment problems should be investigated. Whether personnel minimally meeting the current verbal and reading ability standards will be able to compose accurate non-vocal reports using these automated C<sup>3</sup> systems must be empirically resolved.

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#### CONCLUSIONS

Based on the tactical training requirements of the platoon leader's mission training plan, MTP 17-15-1, this analysis has documented the pervasive impact of automated C<sup>3</sup> systems on the current tasks, subtasks, and standards associated with platoon leader performance. Automated C<sup>3</sup> systems will affect an increasing number of current platoon leader task and training requirements. And the impact of these automated C<sup>3</sup> systems is clearly not limited to the category of C<sup>3</sup> tasks, but extends to each of the fundamental categories of lower echelon maneuver warfare included in MTP 17-15-1.

A primary conclusion of this analysis is that these automated  $C^3$  systems will substantially reduce the current task and training requirements associated with small unit leadership. This reduction will be accomplished by automating, or at least partially automating, many of the time-consuming and repetitive manual and cognitive tasks required for planning, monitoring, and

reporting combat operations at the lower echelon. In addition, this analysis has identified, in a general way, some of the unique training requirements associated with the operation and utilization of these automated  $C^3$  systems.

For nonresident training it is concluded that the computer-based nature of these automated systems provides an excellent medium for embedded training programs. The initial priority of this embedded training is a tutorial program that provides users a clear and self-explanatory introduction to the utilization and capability of all display and control functions provided by the automated command, control, and communication system. A more comprehensive embedded training package should provide users the opportunity to interactively practice the utilization of these C<sup>3</sup> capabilities in the context of realistic mission scenarios and exercises.

It is also concluded that for residential training, computer-based instructional (CBI) programs be developed in support of these automated C<sup>3</sup> systems. These CBI programs should include the training components described above for embedded training, but also provide a more comprehensive and adaptive training package. In particular, this CBI should be tailored for various users and multiple levels of training, from preliminary to advanced. This computer-based instruction should also include such instructional features as self-paced and adaptive training, immediate feedback and knowledge of results for users, and an evaluation of user proficiency for instructors. To reduce the system costs associated with these training requirements, it is noted that this CBI could be developed to operate on the Electronic Information Delivery System (EIDS) which is the Army Standard for CBI.

Finally, it is recommended that the development of these automated training systems should be pursued as quickly as possible. To proceed beyond the level of preliminary analysis to a more formal set of training requirements for automated  ${\bf C}^3$  systems, prototype systems must be extensively utilized and tested by both users and professional trainers. In particular, the issues of informational overload and personnel assignment and selection can only be accurately assessed when operative systems are placed in the hands of potential users and trainers. Automated training systems in residential and non-residential settings could then be used not only in support of training for currently fielded  ${\bf C}^3$  systems, but also as a test bed for ensuring that both user and training requirements are included in the design and development of future automated  ${\bf C}^3$  systems.

By considering now the potential training requirements of future automated C<sup>3</sup> systems, the Army may better ensure that operator performance is optimized and training requirements are minimized. The timely identification of training requirements, such as those identified in this report, should result in their explicit specification in these systems' source selection documents and Required Operational Capabilities (ROC). The intent of the current analysis, therefore, has been to identify a preliminary set of training requirements that must be continuously addressed and refined as BMS and related automated C<sup>3</sup> systems for lower echelons move through the Life Cycle System Management Model (LCSMM).

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APPENDIX A
PRELIMINARY TRAINING REQUIREMENTS FOR LOWER ECHELON C<sup>3</sup> SYSTEMS

		01111	LOWER ECHELON	AUTONNIED CO	LOWER ECHELON AUTOWITED COMPAND AND CONTROL SYSTEMS	OL SYSTEMS	
PLATOCH LE CATEGORY:	PLATECH LEADER/FLATECH TASKS ATECOMY: Communications, Command and Control (5-111-2-3)	Ommonality   Difficulty	Camonality   1	Difficulty	Ocumonality   D	Difficulty	Stand Alone   Network
TASK: Perf (5-	TASK: Perform platoon leader's recommalssance (5-III-2-3-1)	W	Ω	ы	Q	ΡΑ	*
SUBTASKS/STANDARDS:	ANDARDS:						
01. And	01. Analyze the Mission To Be Accomplished	<b>co</b>	Ф	Ø	ъ	8.	*
02. Det	02. Determine the Area in Which the Unit Will Operate	85	P	Ø	ъ	gd.	*
03. Per	03. Perform a Map/Ground Recornaisesence to Determine the Following:	u	P	υ	Ф	8.	*
ej	Nelds of fire and observation	œ	Ф	<b>8</b> 2,		ಐ	*
å	Oover and concealment	Ø	•	82	יסי	<b>8</b> .	*
រ	Obstacles	<b>L</b>	Ð	ø	"O	8.	*
<b>p</b>	Key terrain	బ	ъ	Ð	ъ	<b>9</b> 2,	*
ů	Selection of terrain features for orlentation (check points)	eo ,	P	ø	ď	25.	*
f.	Overwatch positions	Ø	ъ	o ·	₽	2.	*
ΝÔ	Ocusolidation/reorganization locations	œ	₽	ū,	p	8.	, (* * <b>*</b>
ċ	Average of approach	ø	ᠣ	ø	Þ	<b>E</b> .	*
<b>:</b>	Axis of advence	60	ъ	ø	ъ	<b>8.</b>	*
÷	Weather conditions	œ	Ø		P	<b>E</b> .	*

	TWE	LOWER ECHELON AUTOMATED COMMEND AND CONTROL SYSTEMS	UTCHATTED CO.	FINND AND CONTROL	ROL SYSTEMS	The state of the s
MATOON LEADITY/MATOON TASKS	Ommonality officulty	Opinional Ity	Difficulty	Opported 11v	Difficulty	Strind Alone Network
CAIRIORY: Communications, Command and Control (FIII-2-3)		,				-1
<pre>IASK: Perform platoon leader's recornalssance (5-III-2-3-1) (Outinued)</pre>	W	Ω	ங	Q	V.	* .
k. Specific fighting positions	ω	Ð	O	ď	8.	*
1. Oovered and concealed routes	<b>s</b>	Ф	8	Ð	٤.	*
<pre>m. Target reference points (TRP)/ indirect fire targets</pre>	20	Ф	a	q	E.	*
n. Bigagenent areas	Ø	P	O		83	*
o. Trafficability	<b>S</b>	ģ	£.		<b>cs</b>	*
SUPPORTING TASKS:						
SL 1 Estimate Range Identify Terrain Features (Natural and	œ		<b>6</b> 3	-	<b>©</b>	*
Man-mode) on a Map Determine Grid Coordinates of a Point on a Military Man listing Military Crid Pofermone	ss.		Œ		α	*
System.	e P		æ		ಪ	*
Determine Magnetic Azimuth	<b>6</b> 0 °		10		• •	*
Determine Direction	ed p		es		80	*
SL 3 Identify Adjoining Map Spects	ω		σ		<b>.</b> .	*
Determine Azimuths and Compute Back Azimuths	E. P		es es		) aş	*
Locate an Unknown Point on a Map	ъ		σ		• •	*
Locate your Position on a Map or on the Ground Determine a Location on the Ground by Terrain	e e		æ		<b>c</b>	*
Association	e p		œ		65	*

	IA!		LOWER ECHELON	N AUTOMATED OR	LOWER EXPELOR AUTOMATED CONTINUE AND CONTROL SYSTEMS	OL SYSTEMS	CONFIGURATION
PLATIOCH LEADER/FLATIOCH TASKS	Commonailty   Diff	Difficulty	Commonality	Difficulty	iculty Commonality   Difficulty   Commonlity   Diff	Difficulty	Stand Alone   Network
CAIRCORY: Communications, Command and Control (5-III-2-3)							
<pre>TASK: Perform platcon leader's recornalssance (5-III-2-3-1) (Ontinued)</pre>	ω	<u>.</u>	Q	LÙ	۵	PA	* .
Navigate From the Point on the Ground to Another Point	Ф	8.	P	2	P	8.	*
Orient a Map to the Ground by Terrain Association	ъ	ø	Þ	8.		<b>c</b> 3	*
St. 4 Select a Movement Route Using a Map	œ		ъ	8.		æ	*

			TOWER EXHELON AUTOMATED CONTINUE AND CONTROL SYSTEMS	MICHATED CON	TIMED AND CONTI	OC SYSTEMS		ĺ
	IVI	S	SMI	5	IV/SMI	/VI	CONFIGURATION	
PLATOON LEADER/PLATOON TASKS CATEOORY: Communications, Communications (5-111-2-3)	Commonvality   Difficulty	Difficulty	Ommonality   Difficulty	Difficulty	Commonality	Difficulty	Stand Alone   Network	<u>*</u>
TASK: Perform tactical planning (5-III-2-3-3) (5-III-2-3-1)	ω		Ω	ΡΛ	Q	VA.	* .	
SUBTAXKS/STANDARDS:								
01. Determine the Platoon's Mission	קי	ø	p	2.	Þ	Z	*	
02, Develop Course of Action for the Platoon Based on the Company Plan, and the Factors of METI-T	u u		ਚ	8.		œ	*	
03, Select the Best Course of Action for Mission Accomplishment Based on Advantages and Disadvantages	ω		<b>.</b>	8.		æ	*	
o Od. Prepare Marning Order, FRACO, and OPCNU	ט ס	h?	P	gd.		æ	*	
SUPPORTING TASKS:					•			
SL 1 Determine Grid Coordinates of a Point on a Military Map Using Reference System	ъ	Φ		æ		æ	*	
SL 4 Select a Movement Route Using a Map Use a Map Overlay Prepare a Platoon/Element's Fires in the	on to the	γų	ס פט	8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8. 8		αα. α	* * *	
MX II Plan/Onduct a Screening Mission Prepare a Platoon Defensive Fire Plan Formulate a Platoon Attack Plan	ממפר מ	ŭ		. 8.8.6.		<b>લ</b> લ <b>લ</b>	* * *	

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			LOWER FOLITION	LOWIN FOLIELON AUTOMATED COMMUND AND CONTROL SYSTEMS	MOO OND CONT	ROL SYSTEMS	
FLATOON LEADFRA/FLATOON TAGES  CALEBORY: Communications, Commund and Control (5-III-2-3)	Connected 1ty	IVIS y   Difficulty	Compadity	INS DIfficulty	Qumonality	1-1-1	CANTAGRATION Stand Alone   Network
<pre>TASK: Perform contact point activities (5-III-2-3-5)</pre>	Ω	VA	Q	ΡΛ		<	*
SUBTASKS/STANDARDS:							
01. Prvigate to Contact Point	P	Æ	q	Ð	ъ	o	*
<ul> <li>Establish contact point on an identifiable location on the terrain</li> </ul>	œ		•	Q	þ	E.	*
b. Arrive at contact point in sufficient time to effect the minimum coordination	ਚ	υ	₻ .	<b>E</b> .	ъ	<b>2</b> .	*
c. Use prearranged recognition signals for both daylight and night based on the CEOI and/or						. •	
unit 30r prior to the exchange of any information	Þ	8.	Ð	8.		æ	*
02. Secure Contact Point with Available Security Porces	ဟ		ω		ø		
03. Communicate to Other Contact Party. The specific information is determined by the mission. For example, a passage of lines would include:	P ,	ঘ	Ū	E.		<b>c</b> ;	*
a. Designation of unit(s) to pass	ъ	E.	ъ	ĸ		æ	*
b. Mission of units and tentative battle plans	p	82.	ъ	8.		<b>13</b>	*
c. OPFOR situation	Ð	E	Φ	æ		<b>a</b>	* .

	ŀ			LOWER FOLIETON	AUTOTIVITIED CO.	ICHER EXHELIN AUTOMATED CONTAIN AND CONTROL SYSTEMS	ROLLY AND DESIRED
PLATOON LE CATELORY:	PLAICON LEADEN/PLAICON TASKS ATELORY: Communications, Communications (5-111-2-3)	Commonality	Ormorality   Difficulty	Ommorvality	Difficulty	Ocumentality   Difficulty   St.	Stand Alone   Network
IASK: Perfo	Perform contact point activities (5-III-2-3-5) (Continued)	Q	V	Q	Vd	<	*
	Friendly locations – for day and night	סי	22.	P	8.	Ø	*
ย์	Contract and coordination points	ъ	멅	טי	2	œ	*
ų;	OPs and patrol routes	ъ	E.	Ф	<b>8</b> 2,	α	*
ŵ	Passage points and lanes	ъ	멆,	ъ	8	83	*
	Obstacle locations and types	ס	8.	Ð	82	æ	*
;	Assembly areas	ъ	22.	p	gd.	ជ	*
÷	CS and CSS locations for emergency support	p	ቘ	P	ቘ	co	*
ż	Routes	ъ	點.	Þ	EZ	œ	*
1.	Traffic control points	ъ	呂	סי	8	æ	*
Ė	Recognition signals	,	8.	p	ध्य	æ	*
ů	CEDI information	ъ	82	ਰਾ	cg Cg	cs ·	*
ò	Ontomination	ъ	EC.	Ф	8.	• 63 	*
ď	Type and number of vehicles to pass	Ð	pd.	P	8.	<b>ជ</b>	*
÷	Delineation of responsibilities of passing and static unit	Þ	E.	ъ	<b>E</b> .	<b>.</b>	*

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TOWNS TO THE MINISTER OF THE PROPERTY OF THE P

			LAWIK ELLIELLY AUTUMATED CLEMAND AND CONTROL SYSTEMS	MICHAILL CT	TAND AND CONT	OL SYSTEMS		j
	IVIS	S	IMS	3	IV/SIAI	\1	CONFIGURATION	
'	Commonality	Difficulty	Oxinonality	Difficulty	Oxinorality	Difficulty	commonality   Difficulty   Oxinoxullity   Difficulty   Oxinorullity   Difficulty   Stand Alone   Network	 بدا
CAIBOORY: Communications, Command and Control (5-III-2-3)								ſ
TASK: Perform contact point activities (5-III-2-3-5) (Continued)	Q	Va .	Q	PA		<	*	
04. Navigate through the Appropriate Passage Lane, if applicable	ъ	E.	ਚ	5.	ъ	٤	*	
SUPPORTING TASKS:								
SL 1 Use Chillenge and Password Identify Friendly and Threat (OPFOR) Armored Vehicles	co co		യ യ		φ·p	2	*	

	CANFIGURATION Stand Alone   Network	*			*	*	*		* * *	*
TROL SYSTEMS	PRS/AI Oxurcuality   Difficulty	FA			8.	٤	ጀ		8. 2. 2.	8.
FFWND AND CON	Oxinorality	Ω			ъ	þ	ڻ*		ਹਾਰਾਹ	Р
AUTOMATED CO	lers   Difficulty	Vd			2	ø	ø		51, 52, <sub>0</sub>	Ð
LOKER ECHECK ALTONATED CONTIND AND CONTROL SYSTEMS	Onmanitty	Q			P	р	Ф		פ פי פי	P
	Ormorality   Difficulty   Ormarality   Difficulty	гı			ပ				o o	
1010	Omionality	Q			ъ	ω	ω		<b>૦૦</b> ૦	s,
•	FLATOON LEADER/FLATION TASKS CATEORY: Communications, Communications (5-III-2-3)	TASK: CONDUCT rehearsals for current mission (5-III-2-3-6)	SJBTASKS/STANDARDS	01. Ornduct Relearsals Which Do Not Interfere with Subordinate Unit Troop-Leading Procedures and/or Preparations for the	Actual Mission	02. Oxmplete the Rehearsal per the Time Schedule	03. Identify and Correct Mistakes during the Rehearsal	SUPPORTING TASKS:	St. 3  Prepare to Oxduct Training Oxduct Training Evaluation the Oxduct of Training Provide Insut Oxcerning the Status of	Training

DENDA SEMOL	1915   Oxmorability   Difficulty   Oxmorability   Difficulty   Oxmorability   Difficulty   Stand Alone   Retwork   2-4)	2-4-4) D E D FA D PA *		* sed p sed p	30 × 8 vd p s	renues y of ilt ilt ilt int on s d pa pa **		deliver         fally         mal         with the .         I         ment       8         d       pn         e       4	ally lope and
				w	w	ω		ω	
	MATOCH LEADER/FLATOON TASKS  CATEORY: Defensive Operations (5-111-2-4)	IASK: COCUPY a battle position (5-111-2-4-4) (5-111-2-3-5)	SUBINAKS/STANDARDS:	01. Perform Tactical Planning, Nap/Ground	a. Recornoiter the terrain in 30 minutes or less per BP	b. Select BPs based on a thorough analysis of likely OPCN avenues of approach, and the ability of the IP to offer line-of-sight engagements on an OPFON moving on a given avenue of approach (MEIT-I)	<ul><li>Within the limitations of the terrain, the RP should:</li></ul>	(1) Enable the platoon to deliver effective fires (especially flanking fires at optimal ranges) in accordance with the associated fire control technique (TRP, engagement area, etc.)	(2) Provide cover, (especially hull-down or reverse slope positions) concealment, and

	•		- 1	L FOILTON AD	DIVITED COPE	ICMER FOREIGN AUTOMOTED COPEMED AED CONTROL SYSTEMS	J. SYSITYS		
		SIVI		SE		IV/SIMI	N	CONFIGURATION	VI TUN
PLATOON LEADI		Omnomality   Difficulty		Connewdity   Difficulty	fflculty	Commontellty	Difficulty	Stand Alone   Network	Network
CATEGORY: Del	us (5-111-2-4)								
IASK: OCCUPY (5-111)	<pre>TASK: OCCUPY a battle position (5-III-2-4-4) (5-III-2-3-5) (Ontinued)</pre>	D	(-)	D	PA.	Q	PA		*
J	(3) Not be an obvious target for direct— or indirect—fire suppression	ω		p	٤	ъ	٤	*	
J	(4) Have adequate concealed routes in and out	Œ		P	. E	p	. &	*	
J	(5) De large enough for the force assigned	co		ď	v	Ð	8.	*	
ν., •	Select BPs in depth	W		Ф	٤	Ф	Z.	*	
S	Select graphic control measures that:	••							
	(1) Are located on or in proximity to a likely CPFOR avenue of approach	ω		יסי	£		89	*	
J	(2) Permit targets on thom to be engaged and hit by at least one of the weapon systems whose fires it is designed to engage	<b>6</b>		P	ደ		60	*	
J	(3) Enhance a concentration of direct-fire weapon systems	œ		p	٤.		<b>co</b> .	*	.÷
Č	(4) Are planned in association with obstacles (natural, marmade, or planned) that will enhance weapons effects (i.e., increase flank engage- ments, deny cover, etc.)	ω		च	v	ਹ	<b>8.</b>	*	·

MATICAN LEADER/FLATICON TASKS	<pre>(f: Letasive Operations (5-111-2-4)  CCUPY a battle position (5-111-2-4-4) (5-111-2-3-5) (Ontinued)</pre>	(5) Are marked by readily identi- flable terrain features on the map	(6) Provide sufficient control measures to enable the platoon leader to control the battle, without saturating the map	Issue a Five-Paragraph ORORD that covers, at a minimum:	6. Sequence and passage of covering force or other units, as appropriate. Passage lame, contact point, and recognition signals should be included	b. Priority of direct-fire angagements	c. Degree of control imposed on rext lower echelon	<ul> <li>Graphic portrayal of anticipated engagement initiation (engagement areas, etc.)</li> </ul>	<ul> <li>Required rate of OPFOR destruction by phase for successful mission accomplishment</li> </ul>	f. Disengagement scheme	
Onnovality	Q	. <del>a</del>	p W •	rs, d	ite. Wod d	P	ס	<del>0</del>	p	p	
IVIS y Difficulty	ម		Đ	Ð	ú	ů	Đ	E	ū	Ð	
S IMAR FOIFIGN AUTOMIND CONTINUES   1867   1867   1867   1868   1867   1868   1	a	Q	ъ	p	Q	Φ	þ	P	р	Ģ	
Ownwallty   Difficulty   Comment to   Diffic	<b>V</b> 3	o	٤.	2.	٤	ø	E.	E.	o	ø	
TEMED AND CERTIFICE.    PERSON   PERSON	O	~	₽	₽	ਹ	•	ত	פ	ਫਾ	Р	
ROL SYSTEMS //AI	FA	Q	, <u>e</u>	. E	. 8	. E.	<b>E</b> .	E		L E	
OL. SYSTEMS  AT CANFIGURATION DIFFICULTLY COMM Along With the		*	*							r	•

			מנשמז איאטז	LOGIN EXHILTY ALTOWATED CONTINUE AND CIVINGL SYSTEMS	FIMILI AND CAT	INOL SYSTEMS		ĺ
FLATOCH LEADER/PLATOCH TASKS	Ocumentality Difficulty	15 Difficulty	Osmounlity	Difficulty	Commontal Ity	Commonality   Difficulty	Stand Alone   Network	بدا
CAIBOARY: Defensive Operations (5-111-2-4)								
IASK: OCCUPY a battle position (5-III-2-4-4) (5-III-2-3-5) (Ocutinucd)	۵	ш	Q	PA	a	V.	*	
g. Location type, and NLT constitution time of prestocks	p q	ę,	ਰ	٤	ď	æ	*	
h. Movement and BP occupation plan	P	o o	ъ	ψ	ਚ	덦	*	
03. Do Not Exceed the 1/3 Rule when Planning for the Operation	so.		P	ø	ъ	۶.	*	
04. Submit an Initial Fire Plan to Compouny Commander within 30 Minutes	ď	더	P	٤		æ	*	
05. Conduct Movement to the RP IAW Novement and BP Occupation Plans and Prescribed Times	ъ	8.	P	8.	ъ	8.	*	
06. Occupy the BP	ß		ъ	ĸ	v	٤	*	
a. Elements approach from the rear of the BP	ω		<del>Q</del>	Đ	סי	٤	*	
<ul><li>b. If OPs have not been previously established, they are immediately established</li></ul>	ω,		Þ	E.	٠	E.	*	
c. TCs submit sketch range cards to platoon leaders that incorporate sectors and TRPs designated by the platoon leader, within 20 minutes of occupation	Ð	8.	ਚ	도 . 도		<b></b>	*	
07. Prepare Tank Fighting Positions:	<b>v</b> s		Ø		ω			

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				S	MAR ECHILLIN AM	DOMITED COM	LIMITE FOURTEN ARTORNITED COMMAND AND CONTROL SYSTEMS	SYSTEMS		
			IVIS		Ski		IV/SMI		O THICHMITCH	3
מנענו	ĭ IE		Omnorality   Difficulty		Commercially Difficulty	If Iculty	Oximmulity   Difficulty		Stand Alone   Potwork	twork
CATECO	ιχ: 1	CAIRLANY: Defensive Operations (5-111-2-4)								
TASK:	( <u>Y</u>	OCCULY a buttle position (5-III-2-4-4) (5-III-2-3-5) (Ontinued)	Q	គ	د	ΓΛ	۵	۲		*
	<b>6</b>	Ornouflage "primary" fighting position, clear fields of fire, and recornoiter route to hide position within 30 minutes	ω		ω		Ø			
	۵	Recornolter "alternate" and "supplementary" fighting positions including routes from primary within 60 minutes	so		P	<u>E</u>	ਚ	٤	*	
	រ	On the platoon's subsequent BP, mark a primary fighting position and recommoster routes to same within 2 hours	Ŋ		ਹ	ĸ	Q	٤	*	
88	Esta thro	08. Establish Chemical Agent Alarm Systems through the Platoon within 90 Minutes	ω		ω		ω.			
8		Establish fot Loops and Wire or Radio Communications to OPs (platoons/sections)	ω		v		ø			
10.	Ocor Plat	10. Ocordinate with Adjacent Tanks and Piatoons:	P ,	8.	٦	E.		æ		*
	<b>.</b>	Overlapping direct- and indirect- fire	Ф	٤	p	8		<b>©</b>		*
	<b>.</b>	Overlapping observation/security plans (OPs, patrols, etc.)	Þ	<u> </u>	p	S.		æ		*
	;	Obstacle emplacement	ਹ	٤	p	2		ଷ		*
	d.	Location of flowik elements	Р	a <u>.</u>	q	8.		в		*

CERTE STREET	Oximated ty Difficulty Oximerality Difficulty Oximerality Difficulty		D PA D	ed p w p	p tel p	p e p	S	so so	p ed p o p	ad p ud p	d ed ba d	p ud p ə p	p vd p a
	MAIDON LEADEN/PLATOON TARKS (S-111-2-2)	(	INN: Will B bottle position (>111-2-4-4) [ (5-111-2-3-5) (Ontinued)	e, Routes out of IP	<ol> <li>Recommofter Subsequent BPs, to include routes to and from battle positions</li> </ol>	12. Omplete Reboarsals and Nocessary Preparations and Markings of IRs	13. Emplace Local Obstacles that Support the Platoon Battle Positions	14. Perform Immediate Buplacement of Reinforcing Obstacles upon Effective Attachment of Assets	15. Perform Minor RP Adjustment	Mjustment is reported graphically IAV fire plan submitted to higher hendquarters	16. Execute Maintenance, Resupply, and Rest Plans as the situation permits	<ol> <li>Prepare to Oorduct One of the following Actions:</li> </ol>	a. Deliver effective fires on targets  IAW the designated fire control  technique (TRP, engagement area, etc.) indicated on respective execution mutrices

•			TOWER FORFICE	AUTOMATED CO	LOWER ECHELCH ALTICHATED COMMEND AND COLURGE SYSTEMS	ROL SYSTIMS		
	ΛI	IVIS	2	PFIS	PAR	Pris/AI	NOTIONITION	z
CAIRMY: Lefensive Operations (5-111-2-4)	Commonality Difficulty	Difficulty	Commonality	Omnowilty Difficulty	Commondity	Commandity   Difficulty	Stand Alone   Net	Network
IAR: (XXJFY a lattle position (5-III-2-4-4) (5-III-2-3-5) (Continued)	Q	បា	Q	۲٩	۵	ž		*
<ul><li>b. Oxvlut lrug-range observation from covered and oxicealed positions</li></ul>	ယ		ø		ဟ			
c. Nove within the BP on concealed routes so as to avoid detection	w		₽	٤	P	£		*
<ul> <li>d. Identify positively terrain features associated with graphic control measures, under all visibility conditions</li> </ul>	Ð	Q	ਦ	£.	р	٤	*	
SUPPORTING TARKS:								
St. 1 Comouflage Equipment Camouflage your Defensive Position Fractice Noise, Light, and Litter Discipling Select Temporary Fighting Positions	<b>a</b> w w w		σααα	<u>E</u>		Đ	*	
SL 2  Employee and Recover Field Expedient Warning Devices Supervise/Evaluate Construction of a Fighting Position	ω ω		w w		ω ω			
SL 3 Supervise Preparation of a Squod-Size Element's Defense Position Establish an Observation Post	ഗ ഗ		თ -დ	v	<b>v</b> P	£.	·	*

	CINFIGURATION	Stand Alone Network		*	*			*						
VITROIL SYSTEMS	IWS/VI	Commondity Difficulty S		ΓĀ	<b>5</b> 5 63			æ						
PWID AND CO	M	Commonality		Q			ω		ı	w	Ø		s	•
STATES TOTAL NATIONALIED CONFINED AND CONTROL SYSTEMS	IMS	Difficulty		PA	8. S.			84						
DAFIR POSTEON	2	Commonwillty Difficulty		Ω	ਰ ਰ		တ	þ	,	so.	Ø		ĸ	
	IVIS	Difficulty		ស	<b>E. E.</b>			ᄗ						
	VI IV	Commonality Difficulty		Ω	פי סי		Ø	ס	•	a	ø		ဖ	
		PLATOON LEADEN/PLATOON TASKS	CAIECORY: Defensive Operations (5-111-2-4)	<pre>TASK: COUNTY a battle position (5-111-2-4-4)</pre>	Octobrate with Adjacent Platcon-Size Elements Prepare a Platcon/Element Sector Sketch	MOS 1	Supervise Construction of Venicle Figuring Positions	Coordinate with Adjacent Platcon	Unploy and Activate Platoon Early Warming	Supervise: Anniov Pombechnic Fariv	Warning Devices	Supervise: Buplace and Recover Field	Expedient Warming Devices	

r		TWIC	NOTE ECHETON	LOWER EXHELLY AFICHMITED COMMAND AND CONTROL SYSTEMS	MAND AND CONTI	OL SYSTEMS	MATTER STATES
	Commonality	Difficulty	Comparality   Difficulty	Difficulty	Ommonality   Difficulty	Difficulty	Stand Alone   Network
CALECULY: Force flowering (5-111-2-5)							
IASK: EXECUTE actions at a halt (5-III-2-5-1) (Omtinued)	Ω	ស	D	ោ	Q	Vd.	*
d. Submit status report to higher headquarters once the cause is determined and course of action is							
decided	P	h?	סי	23,	ים	8.	*
e. Perform actions to overcome the impediment to movement:	ਰ	Φ	ъ	8.	Þ	<u>e</u>	*
(1) Proceed on original march plan with edjusted times	ט	υ	Þ	2.	ָּט	84.	*
(2) Stop to consolidate and reorganize	ਚ	ø	ъ	E.	Ð	8.	*
(3) Revert to actions taken during a scheduled halt	'U	စ	p	ø	<del>ט</del>	<b>E</b> .	*
03, Move Out as a Unit at the Designated Time or on Order	P	ø	p	٤.	Ð	٤.	*
SUPPORTING TASKS:							

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Ollect/Report Information Comouflage Your Defensive Position Select Temporary Eighting Positions

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			LOWER EXHELY AUTOWITED CONTINUE AND CONTROL SYSTEMS	AUTOWITED CO	AND OND ON	TROIL SYSTEMS	A STATE OF THE STA
	IVIS		5	2	<u>.</u>	IFIS/AL	
PLATOCH LEADER/PLATICON TASKS	Commonality   Difficulty	Offficulty	Commonality   Difficulty	Difficulty	Compredity	Commonality   Difficulty	Stand Alone   Network
CALEBANA: FORCE DOVERFAIL (2-111-2-5)							
TASK: FERFORM a trctical rood march (5-III-2-5-6) (Continued)	Q	ம	Q	PA	Q	VJ	*
SUBTASKS/STANDARDS:							
Ol. Report Passage of Cattleal Points:	P	o	þ	84		B	*
a. Starting point	P	e)	Ð	23.		ជ	*
b. Checkpoint	p	ov.	ъ	8.		๗	*
c. Release point	р	Ð	ರ	ĸ		α	*
02. Perform Movement within Time Specified in OYOND without Exceeding the Catch-UP Speed	ę	Q	q	æ	P	<b>E.</b>	*
03. Maintain Intervehicular Distances (as specified in the march order, within +25 meters.)	<b>.</b>		Ф	Q	Р	<b>Q</b>	*
04. Move on the Route of March except	ਚ	EC	ъ	bd	Þ	G.	*
a. To react to OPFOR contact	ω,		Ø		ъ	22.	*
b. To bypass obstacles	œ		Ø		р	<b>5</b> 2	*
05. Orient Orew Weapon System to Provide 360° Security Overlap	ω		ω	• •	ъ	8.	*

	J. I.		LOKER FOLITION	ALTICHMIED CO	LIMER EXHELIN ATTOMNTED COMMUND AND CONTROL SYSTEMS	ROL SYSTEMS	
PLATOCH LEADER/PLATOCH TASKS  CATEGORY FORM Manager (5-111-2-5)	Commonality	Difficulty	Commonality	Difficulty	Componed Ity   D	Difficulty	Stand Alone   Network
dimoni: 10to 10toldic (7-111-2-2)							
<pre>TASK: FERFORM a toctical road march (5-III-2-5-6) (Ontinued)</pre>	Ω	គា	Q	ΡΛ	Q	PA	*
O6. Maintain Air Gwards to Scan for Aircraft throughout the Movement	Ø		ω		70	Æ	*
07. Perform a Linkup with the Quartering Party/Contoct Point Elements without Causing a Movement Stoppage of the Remainder of the Column	Ф	Φ	<b>.</b>	Q	₽	8.	*
08. Execute Actions at Halts (IAW 5-III-2-5-1)							
09. Neet Enemy Contact with the Immediate Execution of Action Drills by Both the Tement Under Fire and by Those Glose Elements with Preedom to Maneuver	סי	Q	σ	Q	ъ	<b>8.</b>	*
SUPPORTING TASKS:					,		
SL 1 Conouflage Equipment	ω		ω		ω		
St. 3  Determine A location on the Ground by Terrain Association Nardone From One Point on the Council to		Q	Ð	<u>8</u>	p	된.	*
Another Point  Orient a Man to the Count by Themain	P	8	Q	8.	Þ	<b>S.</b>	*
Association	P	E	þ	뛶		8	*
St. 4 Prepare a Platoon/Element Sector Sketch	Ф	2	p	\$.		æ	*

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				LOWITH ECHILLA	LOWER ECHLICK ALTOWATED CONTANT AND CONTROL SYSTEMS	XFMND AND CA	ATTROL SYSTEMS	
DI AID	MATTON I BADED (DI ATTORI TIARES		IVIS		PMS		IMS/AI	CONFIGURATION
CVIEDO	(11-2-5)	Oximotrality	lity   Difficulty	Crimmality	Difficulty	Commonalli	Ownorality   Difficulty	Stand Alone   Network
TASK:	EXECUTE traveling (5-III-2-5-2)	D	កា	Ω	FA.	Q	PA	*
SUBTASK	SUBTASKS/STANDARDS:							
01.	01. Maintain Orientation along the Designated Route or Axis Using Colum, Line, or Wedge formation	od Jge d	8	ָם	8.	Ф	8.	*
	a. Move continuously	Þ	Ð	p	ĸ	ъ	æ	*
	<ul><li>Maintain interval and dispersion between vehicles as terrain and weather permit</li></ul>	ω		P	υ	Þ	ů	*
4 00	c. The platoon leader initiates movement with visual/radio signal for column, wedge, or line formation	nt ', d	8.	P	8.	ਚ	<b>E</b> .	*
	<ul><li>d. The platoon leader chooses a route Wilch uses all ratural cover and concealment</li></ul>	ω		Ф	82.	٠	æ	*
	e. Individual vehicles use terrain- driving techniques to reduce exposure	9. v		ਰ	8.	q	٤.	*
	f. Vehicles maintain orientation using wingmen concept	t/a		ω		p	뚄.	*
05.	02. Maintain Visual Contact between the Sections for the Duration of the Hovement	æ		တ	•	ω		50
03.	03. Establish Positions for Vehicles:	ъ	ပ	ъ	Ð	p	헍	*
	<ul> <li>The platoon leader positions himself in a position that optimizes his control</li> </ul>	 G	ပ	ъ	Q	p	ደ	* .

CANFICURATION	Stand Alone   Network	*	*	*	*		*	*
ROL SYSTEMS	Conmonality Difficulty	V	8.	2.	e.		<b>E.</b>	8.
FIAND AND CONTROL BMS/AI	Commonality	α	Ф	Q	ּס		ъ	"O
LOWER ECHELCH AUTOWATED COMMUD AND CONTROL SYSTEMS INS	Difficulty	W.	υ	ā	ø		2	
IONER BOILEACH	Commonsality   Difficulty	ū	°C	ъ	۳		q	w
	Difficulty	កា	υ	Ü	Ð		<b>;</b>	
IVIS	Commonality   Difficulty	Ω	ਰ	٥	ъ		ъ	Ø
<b>⊢</b> −	CATECORY: Force Hovement (5-111-2-5)	<pre>TASK: EXECUTE traveling (5-111-2-5-2) (Oontinued)</pre>	<ul> <li>b. The platoon leader assigns areas of responsibility for observation and fire to ensure 360<sup>0</sup> platoon security according to unit 50P</li> </ul>	c. The platoon leader insures $360^{\rm o}$ security for the platoon	d. The tank commander maintains 360° Security for Each Vehicle	SUPPORTING TASKS:	St. 1 Send a Radio Message Identify Friendly and Threat (OPICR)	Armored Vehicles

HILITARY PROCESS DESCRIPTION

person recorded besteering transfer (Schoolog) assess to Besteering (Schoolog)

	•			TOWN EQUELOR	ICKIR EQIDER ADCINITO CHIMAD AND CHIRCL SYSTEMS	WAYD AND CITYI	ROIL SYSTEMS	) INVITAGE PROPERTY
			IVIS	14	IMS	12	INS/VI	
17ATOON LE	SKS	Commonality	Difficulty	Commonality   Difficulty	Difficulty	Commencality	Difficulty	Stand Alone Network
CATELORY: 1	CATELORY: NBC (5-111-2-9)							
TASK: PERF Crosi	TASK: PERFORM a nuclear conteminated area crossing (5-111-2-9-11)	Q	បា	a	FA	Q	ΓΛ	* .
SUBIASKS/STANDARDS:	ANDARDS:							
01. Fre	01. Frepare for Crossing	ω		Þ	o O	פ	٤	*
ď	Place externally stored equipment inside or cover it with available material	w		တ		ω		
۵	Direct individuals who may be exposed to radioactive dust particles to wan protective masks or cover their noses and mouths with bankerchiefs or clean rags.	p se ut	Q	Q	v	P	82	*
i	Establish operational exposure guidance (OEC), ensure all leaders and radiac equipment operators knowit	ω		Ф	Q	P	2	*
ė	Ensure all drivers, vehicle commander and leaders know route of march or have strip maps	ъ Ч	<b>E.</b>	P	<b>Ĕ</b> .		æ	*
ย์	Check radiac instrument	Ø		ω		ъ	<u>5</u> .	*
ų	Place radioc instruments into operation	ω		ω		ω		
02. Cro	02. Cross the Area	ъ	ez.	p	ቘ	ъ	E	*
ซึ่	Avoid stirring up dust, keep out of dust cloud and avoid low ground, overhanging branches and bravy brush to the extent possible	P	Q	P	Φ	ਚ	<b>O</b>	. *

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	•	3171		NOTH FORTON	N ALTUNATED CO	LIGHT ECHTAN ATTOMATED CONTANT AND CONTROL SYSTEMS	ROL SYSTEMS	PROTEIN III WATER BOOK
PLATOON LI	PLATOON LEADER/PLATOON TASKS CATEGORY: NBC (5-111-2-9)	Commonality	Difficulty	Chimorudity	Difficulty	Ownerrality Difficulty	Difficulty	Stand Alone   Network
TASK: PERI	PERFORM a muclear conteminated area crossing (5-III-2-9-11) (Continued)	Q	tr3	Q	¥4	Q	Α	*
ģ	Ocnduct movement buttoned up If consistent with the tactical situation	<b>9</b>	<b>53.</b>	ъ	E.	ъ	<u>8</u> .	*
ບໍ	Conduct radiological monitoring and keep PL informed of contamination level (NBC personnel)	ъ	ø	ď	<b>o</b>	ď	E.	*
ď.	Record dose rate received passing through the area (NEC personnel)	œ		w		p	£.	*
ů˙	Move with vehicles buttoned up and in overpressurized mode (if applicable)	P	8.	Ð	£.	ō	뚄.	*
03. Ext	03. Exit Conteminated Area	Ø		ß		s		
eg G	Discard expendable items that have been contaminated	ω		ß		vs		
•	Perform decontomination, if mission permits	ω		ဟ		w		
រ	Evacuate casualties IAW unit SOP	os ,		s		S		
<b>.</b>	Submit NDC report to the company/ team commender (plateon leader)	Ð	h?	ਚ	Æ	P	<b>.</b>	*
SUPPORTING TASKS:	TASKS:							
St. 1 Send a	St. 1 Send a Redio Message	ъ	h?	ਹ	ጀ	<b>"</b> O	٤	*

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STEMS	CONFIGURATION	Commonality Difficulty Stand Alone   Network	<b>*</b>	* * * * * 2.2.2.5.
LOWER EQUELON AUTOMATED CONTIAND AND CONTROL SYSTEMS	IV/SMI		Q	ם פי פי פי פי פי
AUTOMATED OC	DPES	Difficulty	PA	Z Z Z v
LOWER ECHELOP		Commonality	Q	הא ה ה ה ה
	IVIS	y   Difficulty	ш	Z Z Z
		Commonalit	Ω	0 0 0 0 0 0 0
	THE LAW OF THE PARTY AND THE P	PLAIGH LEADER/PLAIGH TAXS	TASK: PERFORM a nuclear conteminated area crossing (5-III-2-9-11) (Continued)	SL 3  Use an IM-174-Series Radiacmeter Direct the Crossing of a Contaminated Area Use an AN/PDR-27 Radiac Set Prepare and Submit NBO-4 Report Supervise Radiation Manitoring Select a Movement Route Using a Map

	r			LOWER ECHELCR	LOWER ECHELON AUTOMATED COMPAND AND CONTROL SYSTEMS	PHAND AND CON	ROL SYSTEMS		ĺ
	- <b>-</b> r	IVI	۲,		IA:S	341	:≲ŀ	DNFIGUR	
PLATOON LEADIT/PLATOON TASKS  CATEORY: Offensive Operations (5-111-2-10)	1	Commonality	Difficulty	Commonality	Commonality   Difficulty	Commonal 1ty	Difficulty	Stand Alone   Network	¥
TASK: EXECUTE a hasty attack (5-III-2-10-2)	111-2-10-2)	Q	ы	Q	Vd	D	Į.	*	
SUBTASKS/STANDARDS:									
01. React to OPFOR Tresence without Desitation and Send Spot Report	lthout Report	ъ	<i>3</i> 4	đ	ъд	g	8.	*	
02. Initiate Fire and Movement to Destroy the OPFOR Before Being Fixed by the OPFOR	t to Destroy wed by the	g	2.	ъ	92.	Ф	8.	*	
03. Conduct the Assault		Q	Ð	ъ	82	٥	<b>5</b> 2.	*	
a. Ensure that moneuwer elements are overwatched	elements are	ď	Ð	q	82	ą	E.	*	
<ul> <li>b. Use suppressive direct and indirect fire against the OPIOR</li> </ul>	ot and indirect	Ģ	Æ	q	Æ	<del>'</del> 0	Æ	*	
c. Attack the OPFOR at his weakest point i.e., flanks, and ensure sufficient combat power to defeat the OPFOR in detail	ils weakest poin sure sufficient at the OPFOR in	ι <b>τ,</b> d	ψ	ъ	æ	<b>.</b>	2.	*	
04, Continue the Original Mission Having Eliminated the OPIOR Threat	slon llaving at	p ,	Ð	g	<b>E</b> .	Ъ	E	*	
SUPPORTING TASKS:					,				
SL 1 Oblect/Report Information		ъ	된	p	2.	Q	E	*	
MQS II Prepare a Situation Report (SITRUZ) Comfuct a Hasty Attack	ጠፊም)	p p	54 Ed	ים סי	8d FG	P	<b>8</b> E	*	

			DON'TH FOURTON	ATICHMITD CO	LOWER EQUELOR ATTERVALLE COPEAN) AND CONTROL SYSTEMS	NOL SYSTEMS	I SO LEGIS IN BOTH OF STATE OF	1
	IVI	200		N. D. C. C.		TV / NA	Complete Annual Complete Annua	-1-
CAIRCORY: Offensive Operations (5-111-2-10-5)	Componentry	Difficulty	October 11ty	DITTICULTY	Companity	Centrality i Difficulty	i SURIN ALONE I PELWOLK	-1
IASK: FERFORM assault force activities (5-III-2-10-5)	Q	ഥ	Ω.	Vd	Q	<b>V</b> .	*	
SUBTASKS/STANDARDS:								
01. Assault the Objective in such a monner as to seize the objective and defeat the OPFOR in detail or force his withdrawal	Ф	o	þ	<u> 5</u> 2.	g	<u>E</u> .	*	
02. Move along the Best Covered and Concealed Routes to Specific Points	ď	Ð	р	뚕.	q	8.	*	
a. Use terrain to avoid OPFOR fire	P	Ð	ъ	æ	P	BA	*	
b. Use appropriate measure to control fire and movement	ъ	٤	Þ	ጀ	סי	ይ	*	
c. Maintain radio contoct with supporting force to keep up a responsive fire support	p	8.	ਹ	82	•	2.	*	
03. Move as Close to Supporting file as Possible	Ф ,	Ed	Ð	E	ਹ	٤	*	
SUPPORTING TASKS:								
SL 2 Collect/Report Information Move Under Direct Fire React to Indirect Fire	ס ק	و و يع	ט ט ט	g. n n	סטס	<u> </u>	* * *	
SL 2 Prepare/Submit Standard Shelling, Mortaring, and Bombing	p	24	ਰ	<u>E</u> .	Ð	<u>8</u>	*	

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CATRODRY Offensing Counting (5 111 2 10 11	Omnonality	Milloulty	Ommonality   Difficulty   Commonality   Difficulty	Difficulty	Oumonality	Difficulty	Stark
(C-111-7-111-7)							
<pre>TASK: FERFORM assault force activities (5-III-2-10-5) (Continued)</pre>	Q	ш	Q	A.	Q	FA.	<b>-tr</b>
SL 3 Coordinate with Adjacent Platcon-Size Elements	ıts d	8.	Þ	<b>E</b> .		ຮ	*

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	Onitonal	Ommorral fty	AI CAPICARATICA DIfficulty Stand Alone   Network
Scheme of Mereuver that Best errain, CPER Situation, and abilities (platoon leader)  delities (platoon leader)  ough Defensive Fire Haking  of:  tele cover and conceniment  of:  tele cover and conceniment  delities		<u>Ω</u>	*
t Best  t, and  oder)  det)  det  e Force  the  det  det  e G  det  det  det  det  det  det  det  de			
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06. Report Platoon's Actions to Higher	Ę.	<b>.</b> ,	. 8.
od p ud p pracom reader) d pa		ত	*

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$\Xi$ 1 $\Xi$	MATICAN LEADIN/PLANCON TASKS CANDARY: Offensive Operations (5-111-2-10-5)	Character	Omirconflity   Difficulty	·	Ownowality Difficulty		Concordity   Difficulty	/AI Difficulty	CINITORATION Stand Alone   Network	ایدا
••	TASK: PERFORM consolidation activities (5-111-2-10-8)	ы	Ω	딘	Q	ΡΛ	Q	PA	*	
8	SUBTACKS/STANDARDS:									
0	Ol. Assess the Situation and Regain Complete Control of All Elements as quickly as possible	Þ		E	סי	EZ.	Ф	£.	*	
05	02. Eliminate Any OPFOR Elements Remaining on the Objective	ω			ď	ጂ	Þ	٤	*	
2	03. Establish Security with Observation Posts	S			q	8.	ъ	2	*	
<b>X</b>	04. Perform Recommaissance to Improve Security	ω			ů	od	ъ	٤,	*	
Š	05. Prepare for Immediate and Puture Missions	Ъ	1-4	Z	ਚ	E.	סי	æ	*	
ý	06. Position Tanks on Armor Avenues of Approach	ch s			đ	8.	Ъ	£	*	
07.	Execute Preplanned Indirect Fire and Close At Support in support of the Consolidation of the Objective	Đ	<b></b>	ዷ	þ	ዲ		æ	*	
ထ်	08. Report Location and Status to the Next Higher Headquarters (platoon leader)	, ,	1.	h?	ď	ĸ	þ	竖.	*	
œ.	09. Evacuate Casualties, PWs, and Donwyod Equipment in accordance with the OYCNU/ Unit SOP	ಌ	Δ.	8.	P	E	ō	<u>E</u>	*	

		0.1	LIANTE ECHELIN	LIATRE FOURTRY AND CONTINUE SYSTEMS	MAND OND CONT	CATHOL SYSTEMS	(WOTHER DESIGNATION)	Ī
PLATOCH LEADER/FLATOCH TASKS  CATEXORY: Offensive Operations (5-111-2-10-5)	Omnorality   Difficulty	Difficulty	Ottomality	Difficulty	Commonality	Oxinorality Difficulty	Stand Alone   Network	됩
IASK: FERFORM consolidation activities (5-III-2-10-8) (Continued)	Ω	ខ	Q	ΓV	Q	ЬV	*	
10. Redistribute Personnel, Supplies, Ammunition, and Equipment within the Platoon as Necessary to Continue the Mission	ъ	O	Ð	٤	p	된.		
11. Update and Develop Fire Plans to Support a Ontinued Mission. When the objective is to be held for a lengthy period of time, this includes final protective fires (FPF)	Ф	<b>E</b> .	₽	ጂ		<b>Q</b>	*	
12. Execute Chemical Detection Procedures	Ø		w		s			
13. Omtinue to Develop the Position, Camouflage Equipment, Monitor Survey Teams, Initiate Sleep Plans, and Prepare and Submit Routine Reports	ъ	ød	Ð	፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟	"U	<b>E</b> .	*	
SUFFORTING TASKS:								
St. 1 Send a Rodio Message Use Challenge and Password Carouflage Enuloment		h?	၁၀ဖ	ed	n a c	E.	*	
Comouflage Your Defensive Positions Collect/Report Information Evaluate a Casualty	ασα	2.	מ כי מ	Z.	യ യ	ec	*	
SL 3 Establish an Observation Post Supervise Personnel Handling Ammunition	യ യ		p s	σ	o G	<b>&amp;</b>	* * ·	
MQS II Prepare a Situation Report (STINA?)	Q	<i>2</i> 11	p	घ		ಣ	*	